Amendments to the claims:

Claims 1 - 3. (canceled).

4. (currently amended) A piezo-electric drive, comprising a reference part (1) and a drive part (2), a plurality of packets of clamping piezos (3) arranged side-by-side in the form of first stacks of piezo elements ~~arranged in the direction of their stack height~~ disposed between said reference part (1) and said drive part (2) in a pre-compressed state, ~~each piezo-electric drive part (2) being provided with~~ and engaging said drive part (2) via a clamping shoe (32) a stepping piezo packet (4) ~~in the form of~~ connected to said clamping shoe and including second stacks of piezo elements~~,~~ ~~whose~~ with a stacking direction ~~extends~~ extending about normal to the stacking direction of the clamping piezo packets (3) ~~and the stacks being arranged~~ so as to be oriented in the direction of the relative movement between the reference part (1) and the drive part (2), ~~all the stacks of clamping piezos (3) being connected with one end to one of the elements reference part and drive part and, with their opposite free end, engaging the respective other element reference part and drive part, and the stack of stepping piezos (4) each being connected with one end to the same of the elements references part and drive part to which also the one ends of the stacks of clamping piezos (3) are connected, and, with their other end, to the free end of one of the stacks of the clamping piezos, said stacks of clamping piezos being supported each with one end by a common "rigid" component and with their other end biased~~ said reference part (1) being a common "rigid" support component and at least said packets of clamping piezos (3) being supported in a pre-compressed state ~~by~~ on the ~~respective element~~ reference

part (1) ~~or drive part into engagement with the~~ by a bridging plate (5) which is “semi-rigid”, ~~and the “semi-rigid” design of the bridging plate (5) being such that the bridge plate (5) adapts at least in the length tolerance and expansion length range of the individual clamping piezo stacks~~ so as to accommodate in a static state ~~to~~ stack height differences ~~of the individual clamping stack height differences~~ of the individual clamping piezo stacks in a bending-elastic manner, but, in a dynamic state at the given operating frequency, is essentially rigid and during a ~~time-window~~ period, in which in each case one group of clamping piezo stacks is electrically de-activated and not expanded and the other group of clamping piezo stacks is electrically activated and expanded, yields under the pre-compression pressure by ~~not more than~~ only a fraction of the piezo expansion length.

5. (currently amended) A piezo-electric drive according to claim 4, wherein the “semi-rigid” bridging plate (5) ~~is assigned to~~ engages the reference part (1) ~~and engages this part~~ under the pre-compression pressure in a resilient manner and the free ends of the clamping piezo stacks (3) engage the drive part (2) ~~which is designed as the “rigid” component~~.